

Table 4.1:  $T_{measurePDR}$ ,  $T_{evaluatePDR}$ ,  $T_{measureTDD}$ ,  $T_{evaluateTDD}$ , and  $T_{measureCSM}$

DRX cycle length [s]	Number of DRX cycles	$T_{measurePDR}$ [s] (number of DRX cycles)	$T_{evaluatePDR}$ [s] (number of DRX cycles)	$T_{measureTDD}$ [s] (number of DRX cycles)	$T_{evaluateTDD}$ [s] (number of DRX cycles)	$T_{measureCSM}$ [s] (number of DRX cycles)
0.08	4	0.64 (8 DRX cycles)	2.56 (32 DRX cycles)	0.64 (8 DRX cycles)	2.56 (32 DRX cycles)	2.56 (32 DRX cycles)
0.16	4	0.64 (4)	2.56 (16)	0.64 (4)	2.56 (16)	2.56 (16)
0.32	4	1.28 (4)	5.12 (16)	1.28 (4)	5.12 (16)	5.12 (16)
0.64	4	1.28 (2)	5.12 (8)	1.28 (2)	5.12 (8)	5.12 (8)
1.28	2	1.28 (1)	6.4 (5)	1.28 (1)	6.4 (5)	6.4 (5)
2.56	2	2.56 (1)	7.68 (3)	2.56 (1)	7.68 (3)	7.68 (3)
5.12	1	5.12 (1)	10.24 (2)	5.12 (1)	10.24 (2)	10.24 (2)

In idle mode, UE shall support DRX cycles lengths 0.64, 1.28, 2.56 and 5.12 s, according to [16].

4.2.2.8 Number of cells in cell lists

For idle mode cell re-selection purposes, the UE shall be capable of monitoring:

- 32 intra-frequency cells (including serving cell), and
- 32 inter-frequency cells, including
- FDD cells on maximum 2 additional carriers, and
- Depending on UE capability, TDD cells distributed on up to 3 TDD carriers, and
- Depending on UE capability, 32 GSM cells distributed on up to 32 GSM carriers, as indicated in cell information lists sent in system information (BCCH).

5 UTRAN Connected mode mobility

This section contains the requirements on the mobility procedures in UTRAN connected mode such as handover and cell re-selection.

Requirements related to the measurements in support of the execution of the UTRAN connected mode mobility procedures are specified, currently not necessarily for all UTRAN connected mode states, in section 8.

The radio links the UE shall use are controlled by UTRAN with RRC signalling.

UE behaviour in response to UTRAN RRC messages is described in TS25.331.

The purpose of Cell reselection in CELL\_FACH, CELL\_PCH and URA\_PCH states is that the UE shall select a better cell according to the cell reselection criteria in TS 25.304. CELL\_FACH, CELL\_PCH and URA\_PCH states are described in TS 25.331.

5.1 FDD/FDD Soft Handover

5.1.1 Introduction

Soft handover is a function in which the UE is connected to several UTRAN access points at the same time. Addition and/or release of radio links are controlled by the ACTIVE SET UPDATE procedure.

The soft handover function includes a measurement phase, a decision algorithm in UTRAN and the ACTIVE SET UPDATE procedure.

5.1.2 Requirements

5.1.2.1 Active set dimension

The UE shall be capable of supporting at least 6 radio links in the active set.

As described in TS 25.211, the UE may be informed by UTRAN that for one or more links in the active set neither S-CPICH or P-CPICH is available as phase reference and the UE shall thus use the Dedicated Pilot as phase reference. The UE shall then support at least 6 radio links in the active set, out of which up to 4 radio links are such that the Dedicated Pilot shall be used as a phase reference

5.1.2.2 Active set update delay

The active set update delay is defined as the time from when the UE has received the ACTIVE SET UPDATE message from UTRAN, or at the time stated through the activation time when to perform the active set update, to the time when the UE successfully uses the set of radio links stated in that message for power control.

The active set update delay is depending on the number of known cells referred to in the ACTIVE SET UPDATE message. A cell is known if it has been measured by the UE during the last 5 seconds and the SNR of the cell has been decoded by the UE.

And the phase reference is the primary CPICH.

The active set update delay shall be less than  $50+10\cdot KC+100\cdot OC$  ms, where

KC is the number of known cells in the active set update message.

OC is the number of cells that are not known in the active set update message.

If the UE have radio links in the active set that it can not use for data detection (due to low signal level), the UE shall at least every 150 ms search for the radio link

5.1.2.3 Interruption Time

The UE shall not interrupt the data flow when adding, changing or removing radio links to the active set.

5.2 FDD/FDD Hard Handover

5.2.1 Introduction

The hard handover procedure is initiated from UTRAN with a RRC message that implies a hard handover, see TS 25.331 section 8.3.5.

5.2.2 Requirements

5.2.2.1 Hard handover delay

Procedure delay for all procedures, that can command a hard handover, are specified in TS25.331 section 13.5.2.

When the UE receives a RRC message implying hard handover with the activation time "now" or earlier than than  $D_{handover}$  seconds from the end of the last TTI containing the RRC command, the UE shall be ready to start the transmission of the new uplink DPCH within  $D_{handover}$  seconds from the end of the last TTI containing the RRC command.

If the access is delayed to an indicated activation time later than  $D_{handover}$  seconds from the end of the last TTI containing the RRC command, the UE shall be ready to start the transmission of the new uplink DPCH at the designated activation time.

where:

$D_{\text{handover}}$  equals the RRC procedure delay defined in TS25.331 Section 13.5.2 plus the interruption time stated in section 5.2.2.2.

### 5.2.2.2 Interruption time

The interruption time, i.e. the time between the last TTI containing a transport block on the old DPDCH and the time the UE starts transmission of the new uplink DPCH, is depending on whether the target cell is known for the UE or not.

If intra-frequency hard handover is commanded or inter-frequency hard handover is commanded when the UE does not need compressed mode to perform inter-frequency measurements, the interruption time shall be less than  $T_{\text{interrupt1}}$

$$T_{\text{interrupt1}} = T_{\text{tr}} + 40 + 20 \cdot \text{KC} + 150 \cdot \text{OC} + 10 \cdot F_{\text{max}} \text{ ms}$$

where

$T_{\text{tr}}$  is the interruption uncertainty when changing the timing from the old to the new cell.  $T_{\text{tr}}$  can be up to one frame (10 ms).

KC is the number of known target cells in the message, and

OC is the number of target cells that are not known in the message.

$F_{\text{max}}$  denotes the maximum number of radio frames within the transmission time intervals of all transport channels that are multiplexed into the same CCTCH.

Note: The figure 40 ms is the time required for measuring the downlink DPCH channel as stated in TS 25.214 section 4.3.1.2.

In the interruption requirement  $T_{\text{interrupt1}}$  a cell is known if it has been measured by the UE during the last 5 seconds and the SFN of the cell has been decoded by the UE.

If inter-frequency hard handover is commanded and the UE needs compressed mode to perform inter-frequency measurements, the interruption time shall be less than  $T_{\text{interrupt2}}$

$$T_{\text{interrupt2}} = T_{\text{tr}} + 40 + 50 \cdot \text{KC} + 150 \cdot \text{OC} + 10 \cdot F_{\text{max}} \text{ ms}$$

In the interruption requirement  $T_{\text{interrupt2}}$  a cell is known if:

- the cell has been measured by the UE during the last 5 seconds.

The phase reference is the primary CPICH.

The requirements in this section assume that N312 has the smallest possible value i.e. only one insync is required.

## 5.3 FDD/TDD Handover

### 5.3.1 Introduction

The purpose of FDD/TDD handover is to change the radio access mode from FDD to TDD. The FDD/TDD handover procedure is initiated from UTRAN with a RRC message that implies a hard handover as described in [16].

### 5.3.2 Requirements

The requirements in this section shall apply to UE supporting FDD and TDD.

#### 5.3.2.1 FDD/TDD handover delay

RRC procedure performance values for all RRC procedures, that can command a hard handover, are specified in [16].